



Exploiting Synthetic Aperture Radar to map and observe landslides

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California Institute of Technology

Landslides impacting road-corridors

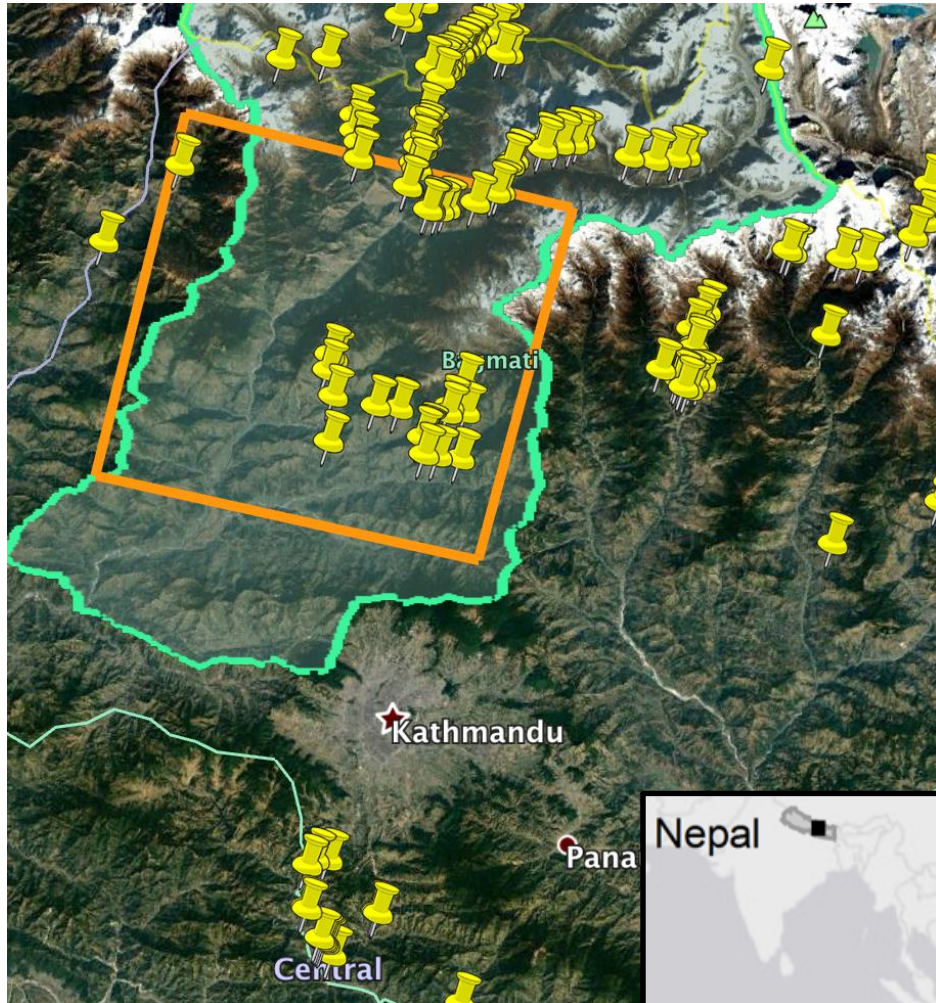
- Thousands of people are impacted each year by landslides
- Poorly designed roads are more prone to landslides
- Local economies are highly vulnerable to inaccessible road networks

Improved understanding on causes & correlation with physical processes requires dense spatio-temporal landslide catalogues

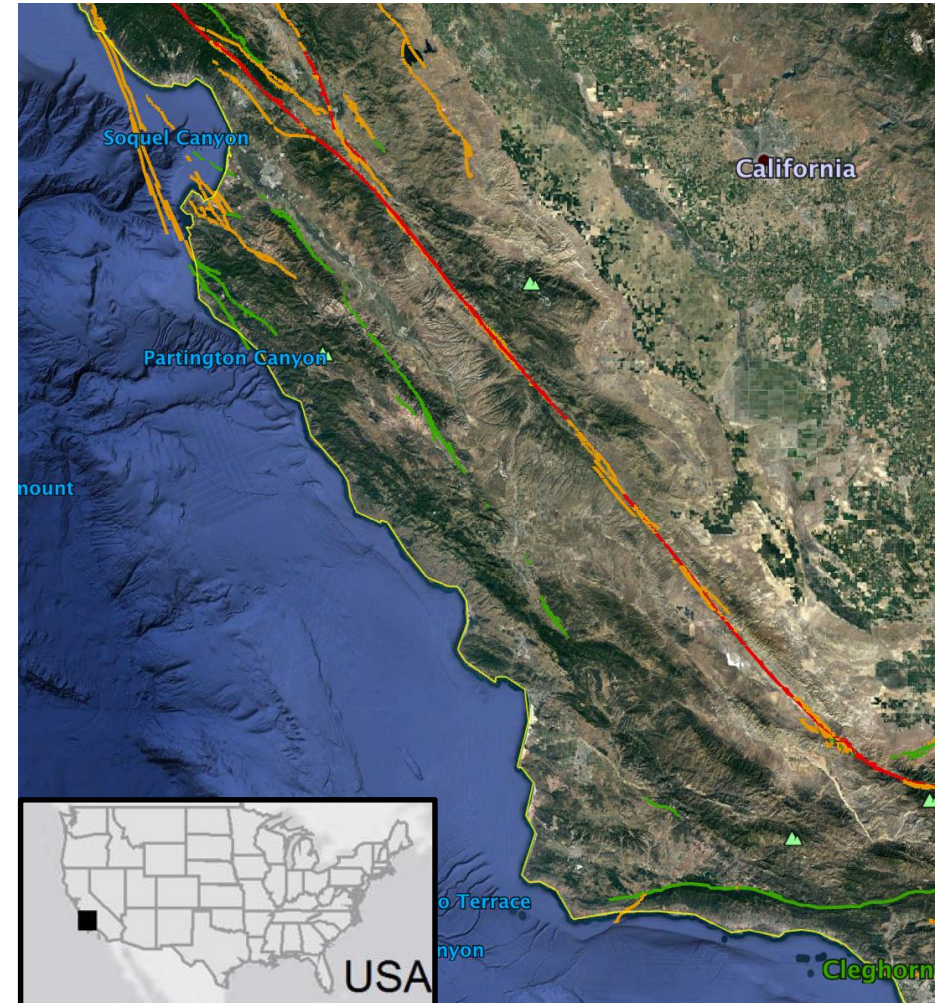


Landslide mapping study areas

Trishuli highway in Nepal



California Pacific Highway-1



Detection of Landslides using Synthetic Aperture Radar

1. SAR change detection (*amplitude/intensity*), InSAR (*coherence*)

Example: Nepal

- SAR resolution (+ coherence estimation window) <-> landslide spatial extent
- Thresholding
- Separate false positives (scattering change e.g. precip, snow, EQ etc.)
- **Critical failure (surface no longer preserved)**

2. Pixel/feature offset tracking

Example: USA

- Needs preserved surface features
- SAR resolution and correlation window <-> landslide spatial extent
- **Fast moving slides (rates > 10th of SAR pixel size)**

3. Time-series InSAR

Examples: Nepal and USA

- Only sensitive to Line of Sight motion
- SAR resolution <-> landslide spatial extent
- **Slow moving slides (i.e. non-aliased rate)**

All sensitive to:

- Geometry (shadow and layover)
- Noise (snow, vegetation, precip., atmos.)

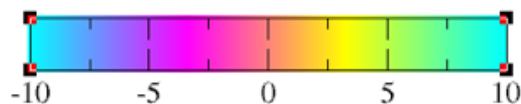
1. Change Detection InSAR

Critical failure (surface no longer preserved)

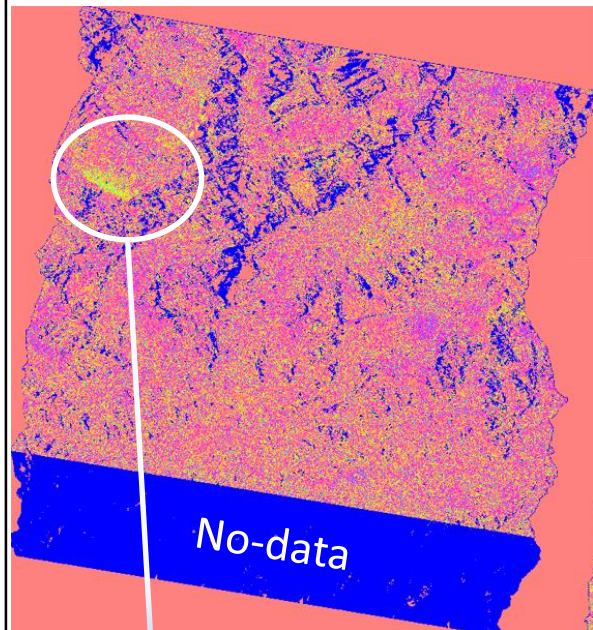
Coherence-Index (April-November)

7-19-31 Oct 2014

$$10 \log_{10} \left(\frac{\text{coh1}}{\text{coh2}} \right)$$

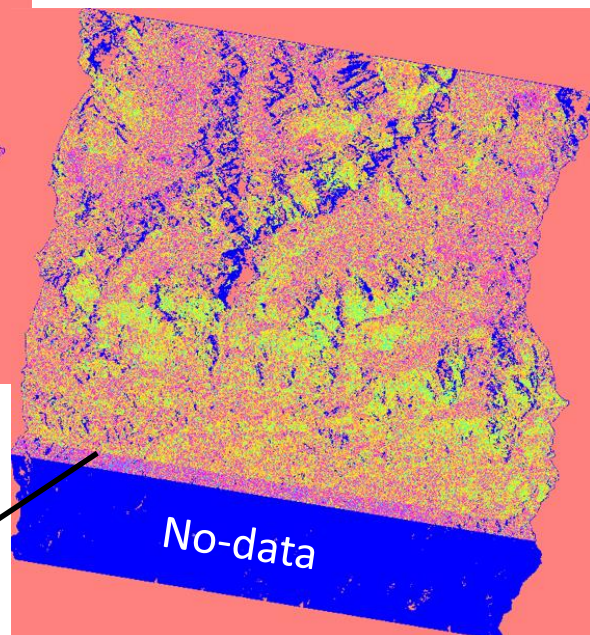


5-17-29 Apr 2015



Snow?

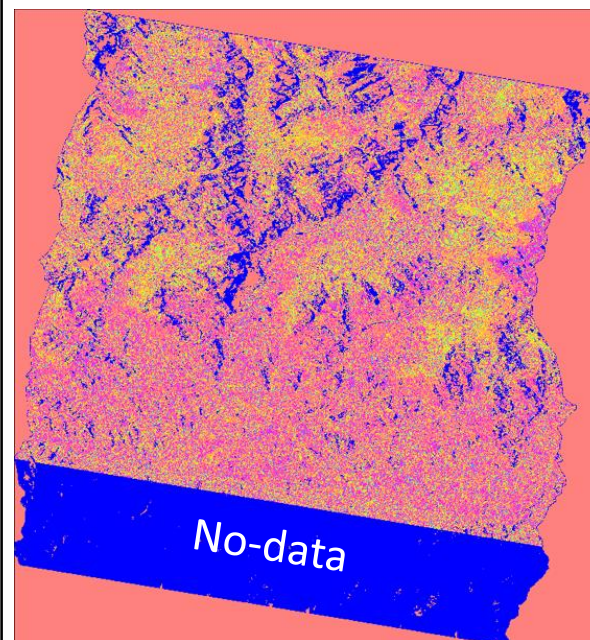
How to separate from
Gorka EQ on 25 Apr 2015?



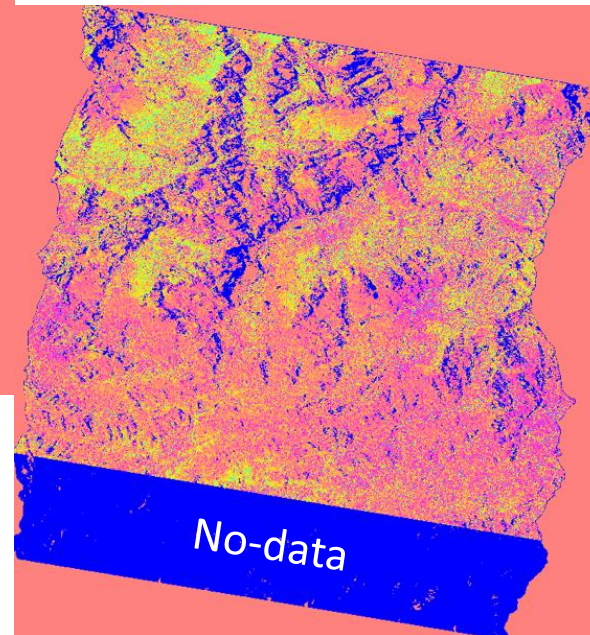
Coherence-Index (Winter/spring)

19-31 Oct, 12 Nov 2014

decorrelation for
winter images



19-31 Dec 2016, 12 Jan 2017



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2. Feature/pixel offset tracking

Fast moving slides

Needs preserved surface features
Requires motion >10% of pixel size

CA Mudcreek landslide (20 May 2017)

PRE (2017-05-16)

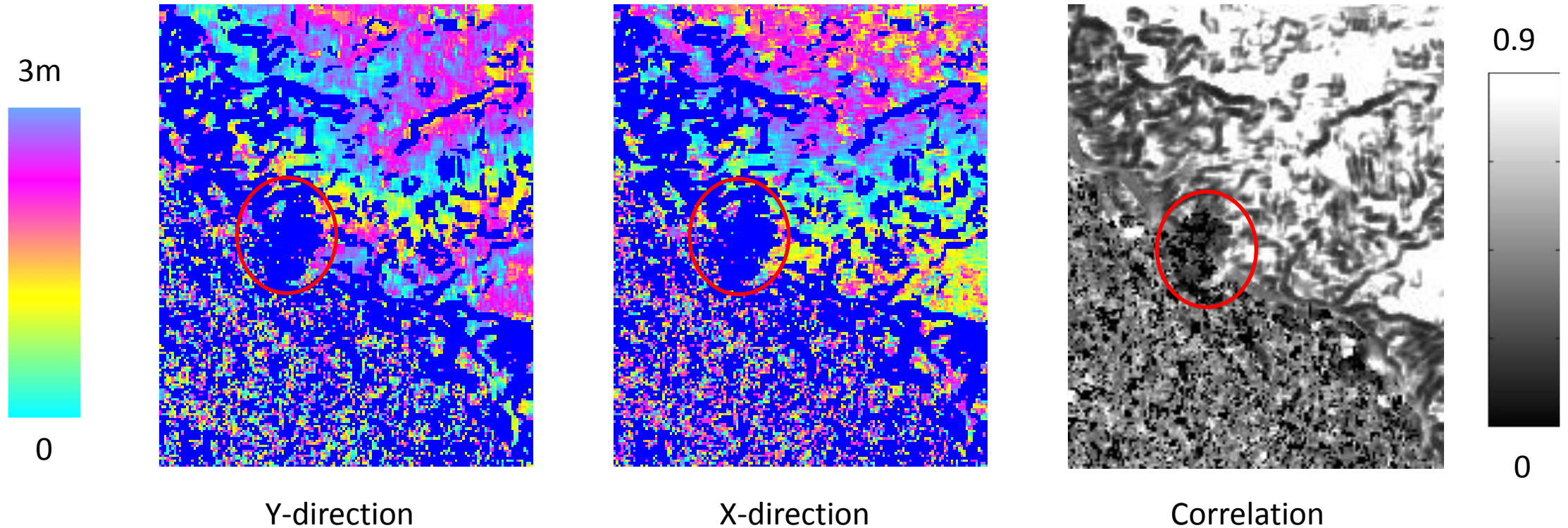


POST (2017-05-31)



Data accessible for free under Planet's Open California Initiative

Pixel offsets



- Landslide completely decorrelated after failure
- Correlation of 0.7-0.8 at least needed for reliable estimates
- Orthorectification artifacts also visible in the offset estimates

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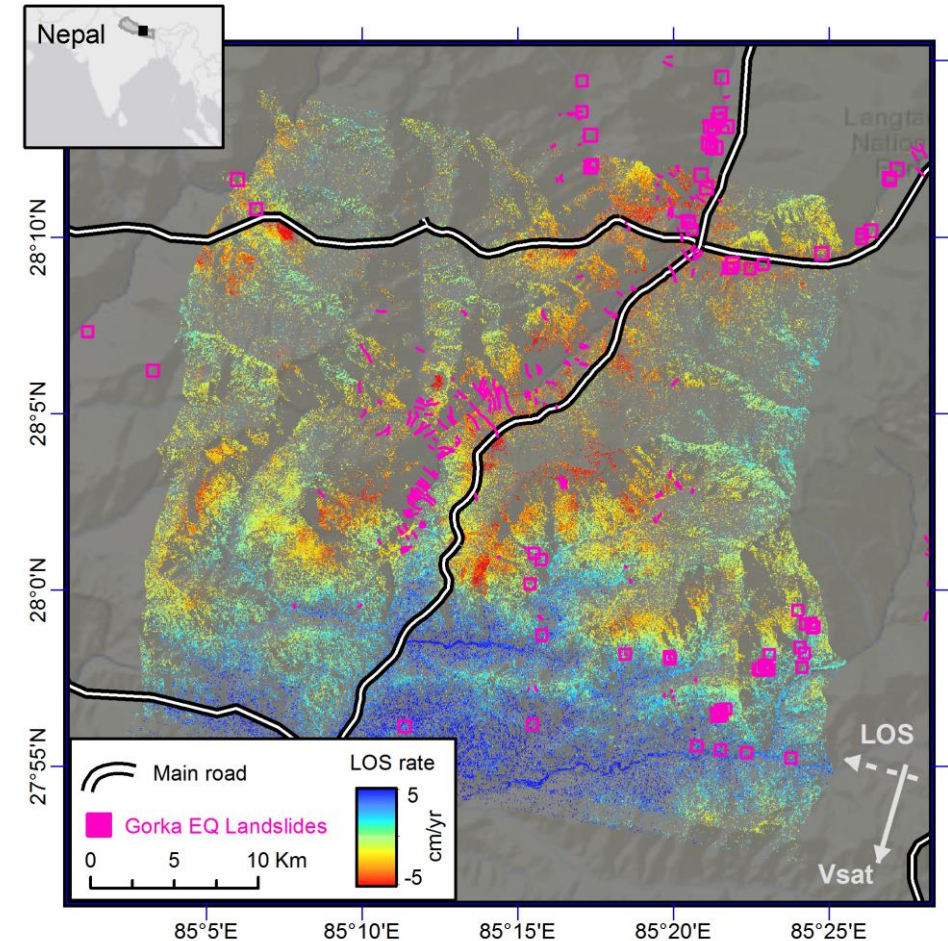
- Geometry (shadow and layover)
- Noise (snow, vegetation, precip., atmos.)

Regional rate maps are difficult to interpret

3. Time-series InSAR

Techniques include: PSI, PS, SBAS, SqueeSAR etc.

- Radar geometry leading to pixel distortion
 - Layover and shadowing effects
- Atmospheric noise
 - Long wavelength spatially varying ($>20\text{km}$)
 - Short spatial wavelength turbulent ($<2\text{km}$)
 - Topography correlated (local)
 - Noise more apparent away from InSAR reference
- Tectonic deformation
 - Interseismic, Coseismic, Postseismic, Afterslip
- Anthropogenic deformation
- DEM errors introduced in processing



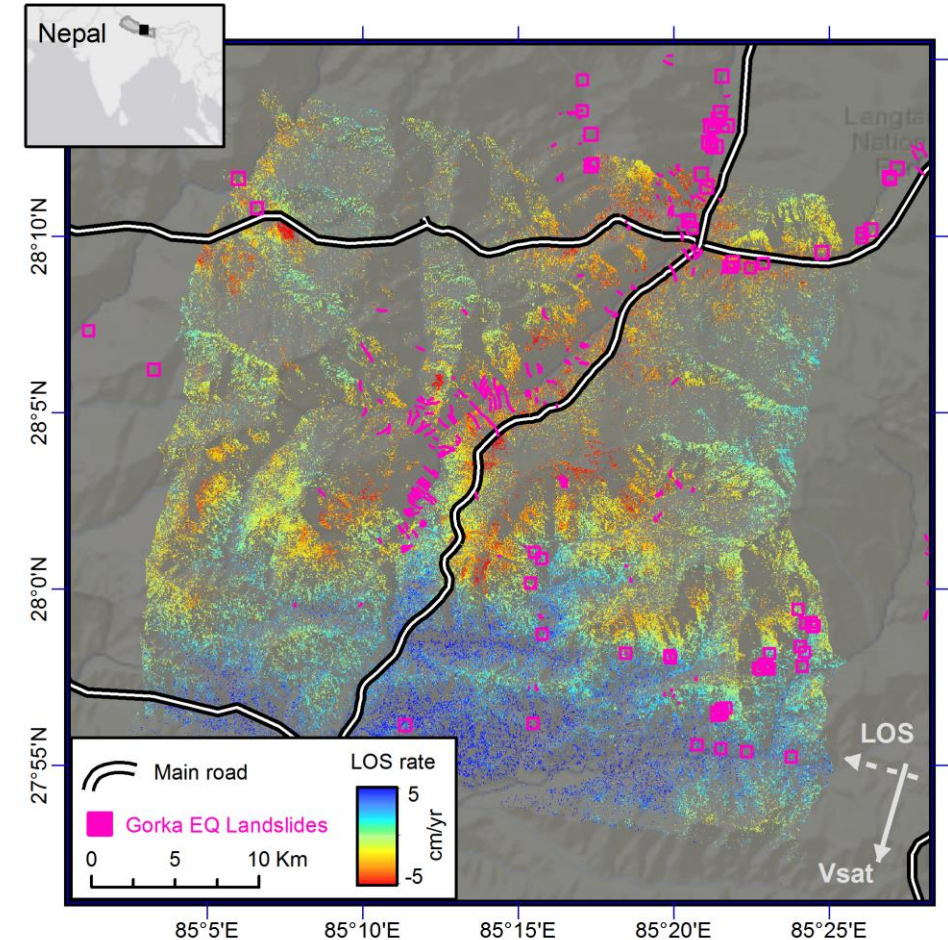
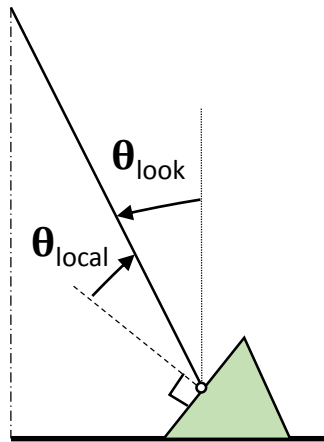
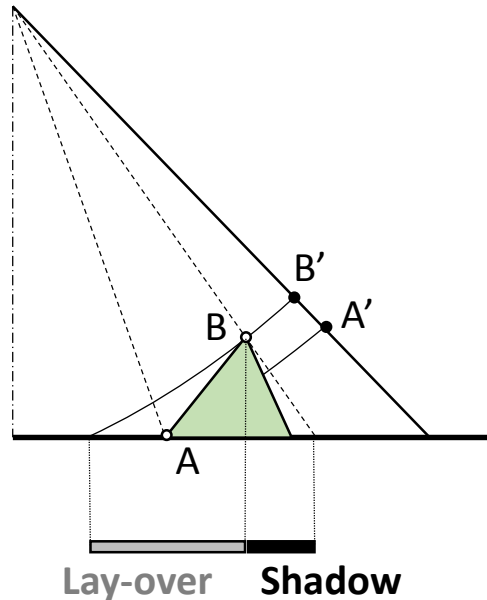
How to handle Radar Geometry?

Mask out pixels that have radar distortion:

- Shadowing (Feature that does not get illuminated by the radar)
- Lay-over (Top of a feature is received before the base of the feature)

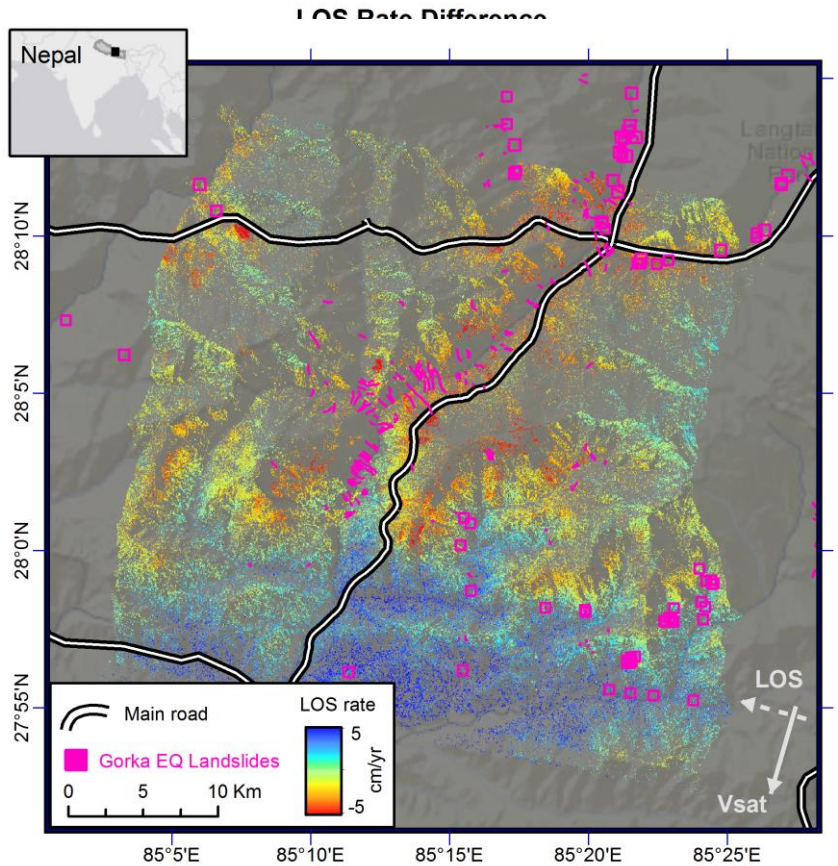
Mask out pixels on flat terrain & slopes insensitive to the radar

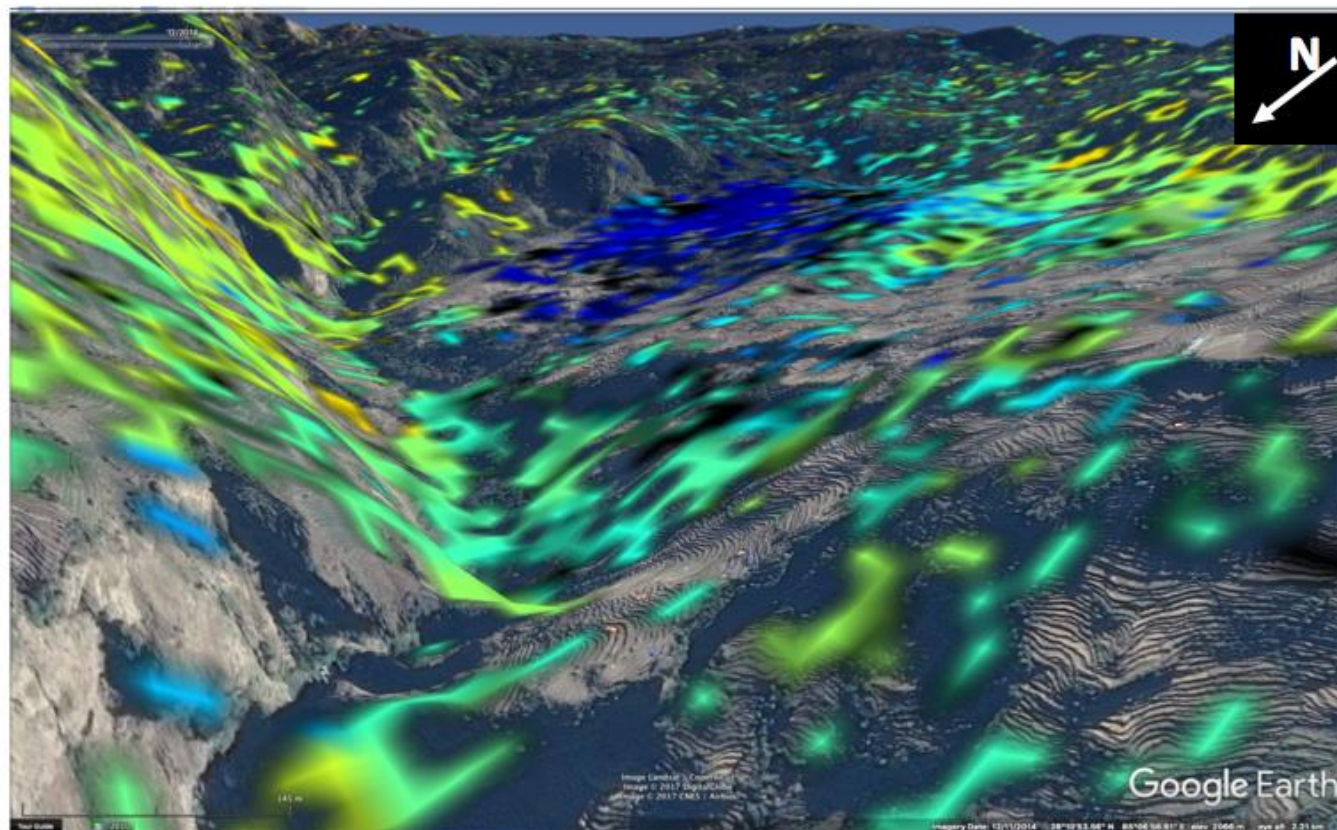
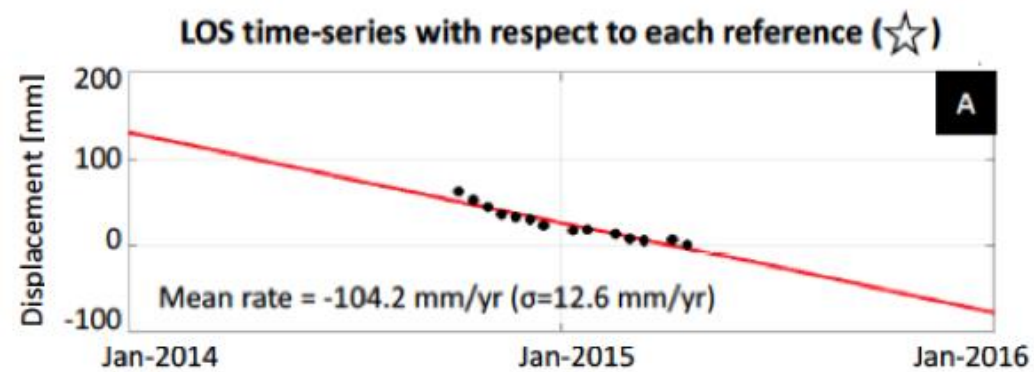
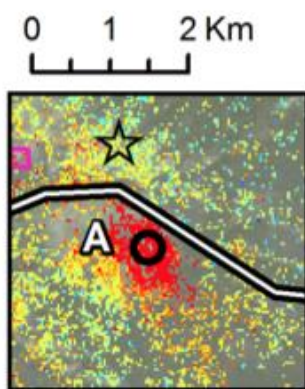
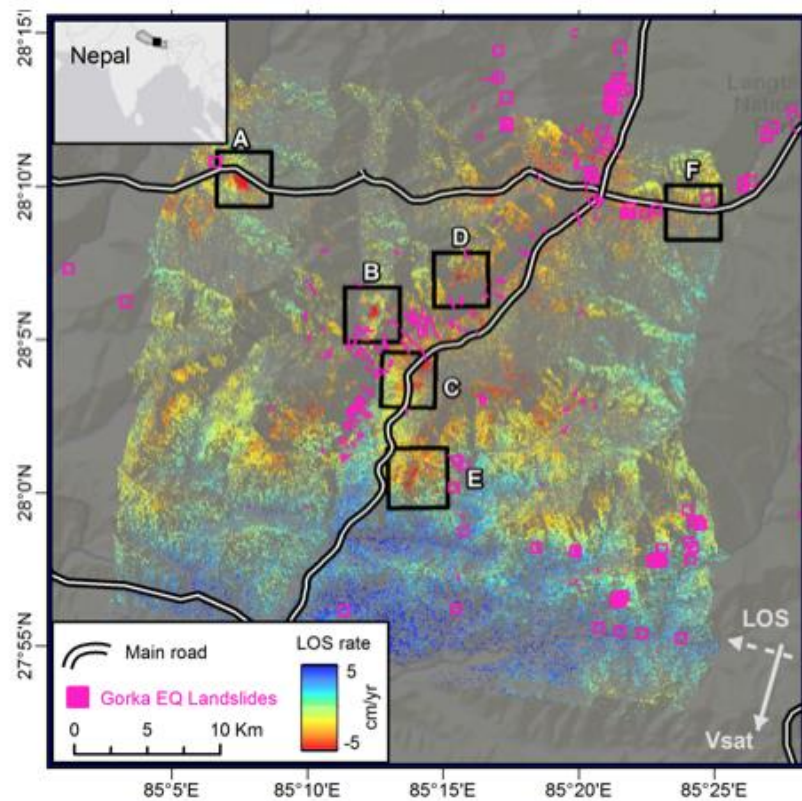
- Remove pixels for which $|\theta_{\text{look}} - \theta_{\text{local}}| < 5^\circ$

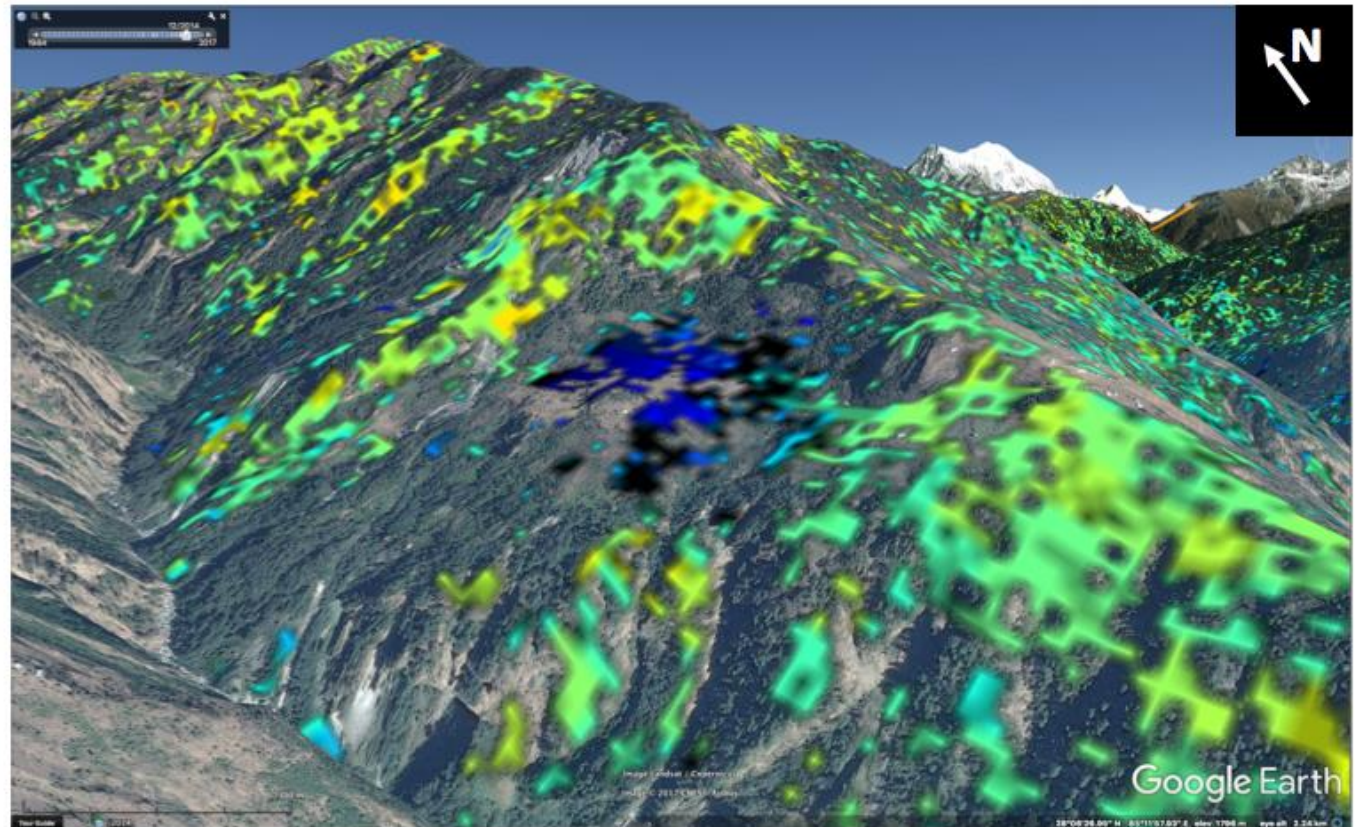
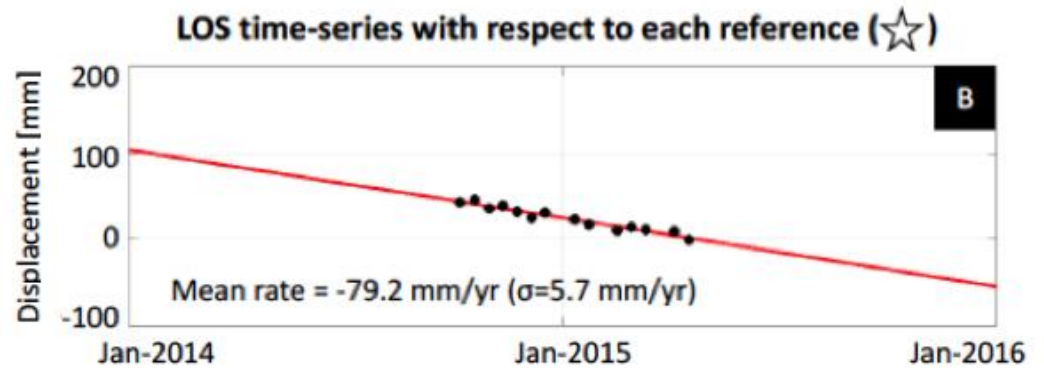
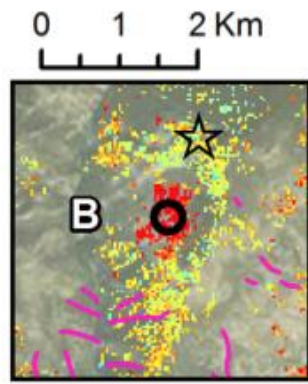
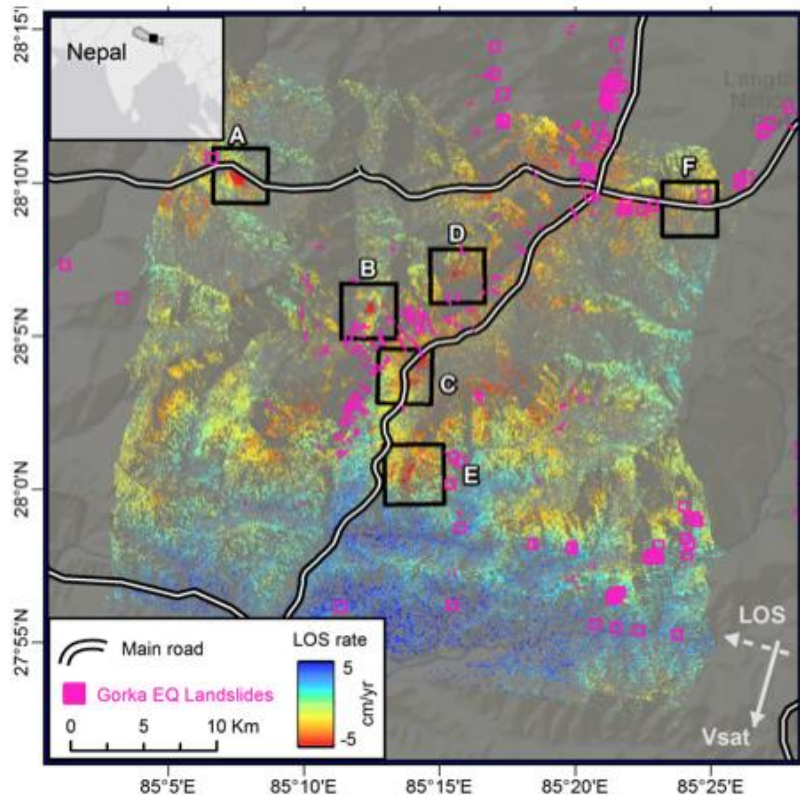


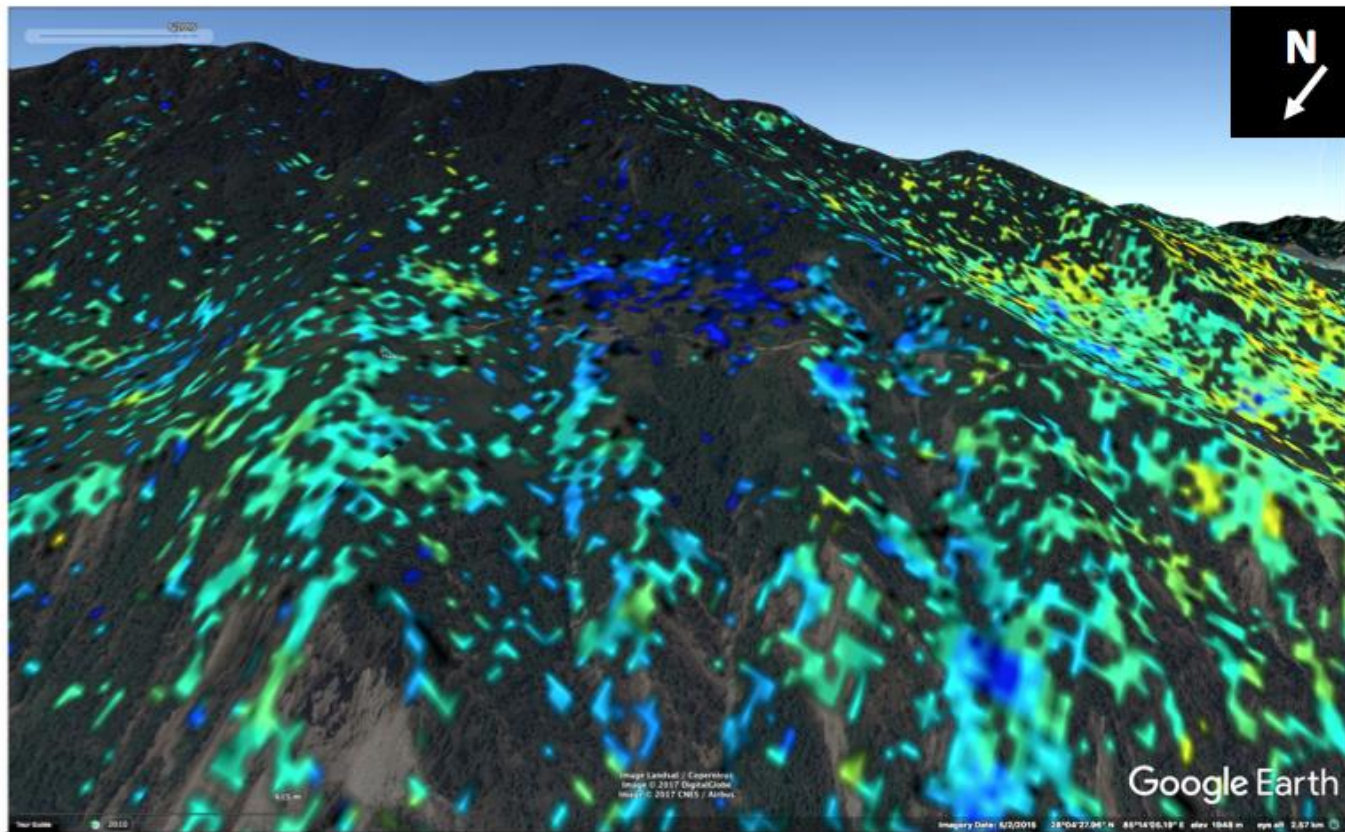
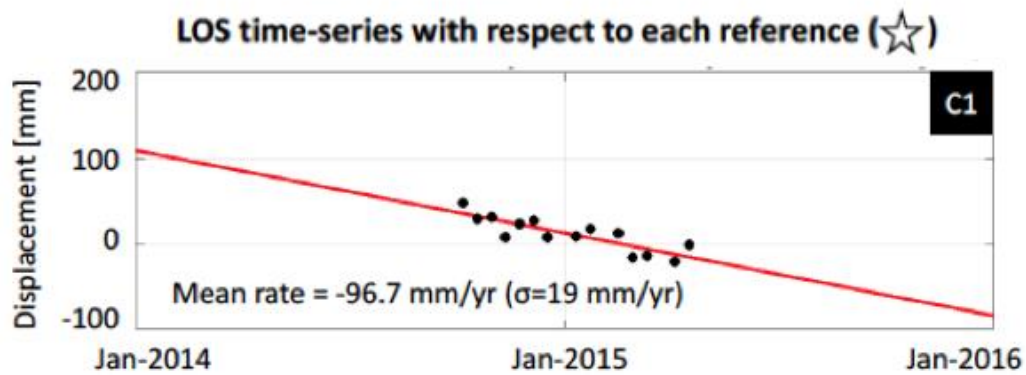
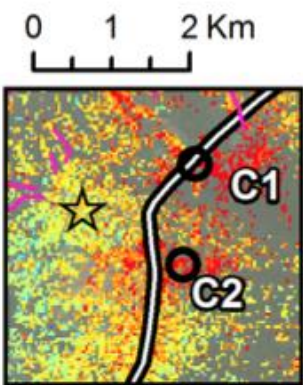
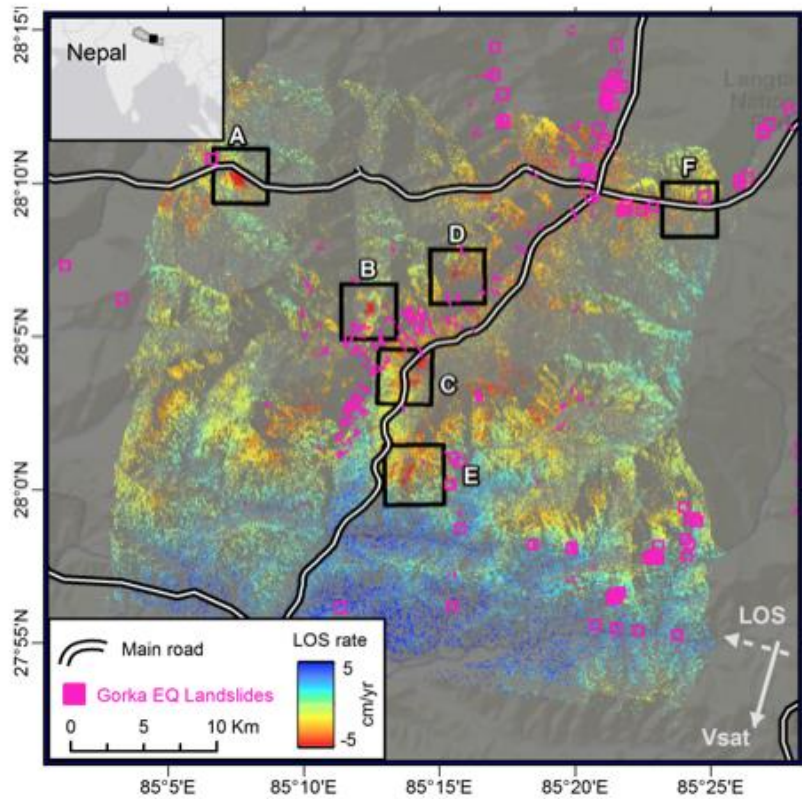
How to distinct noise sources from landslide?

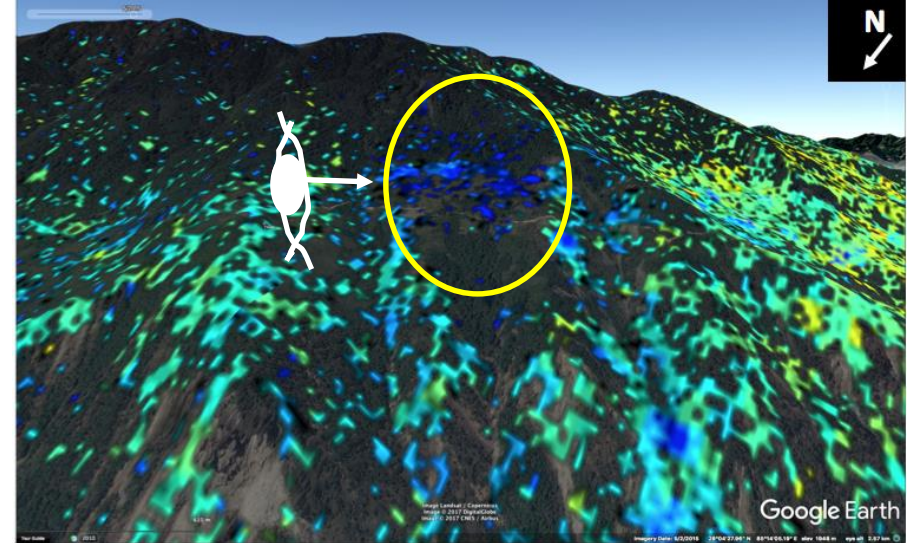
Local double differences cancels out longer wavelength noise signals -> DETECTOR

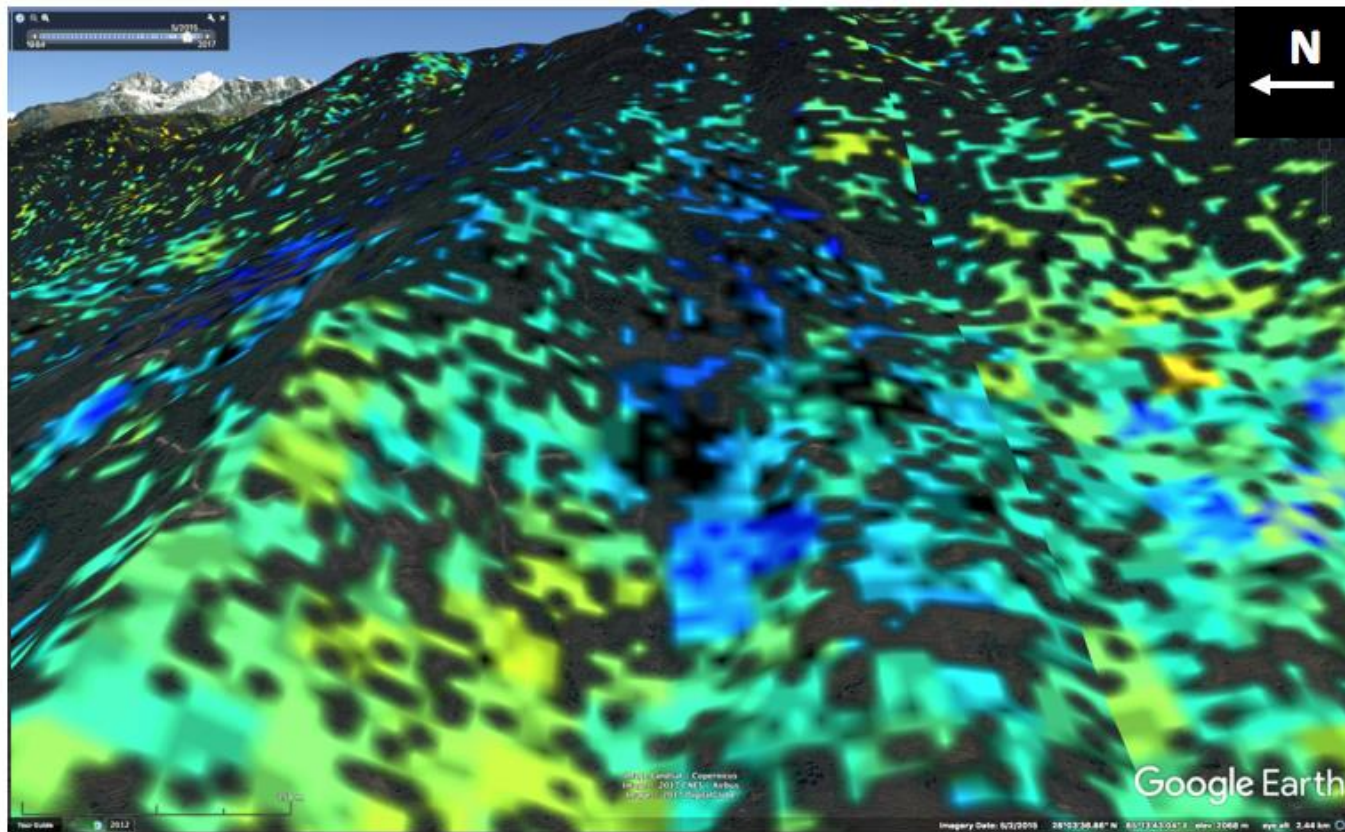
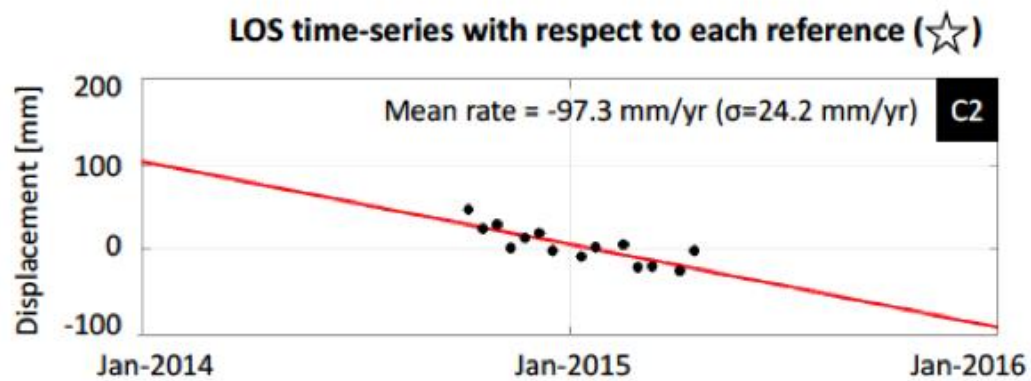
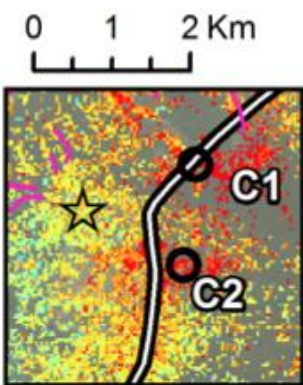
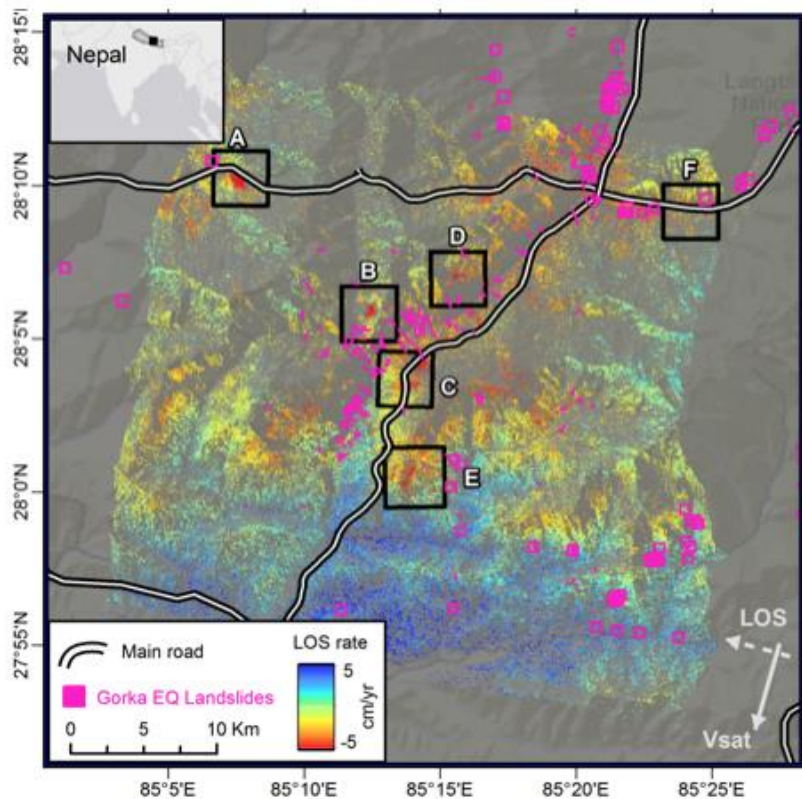


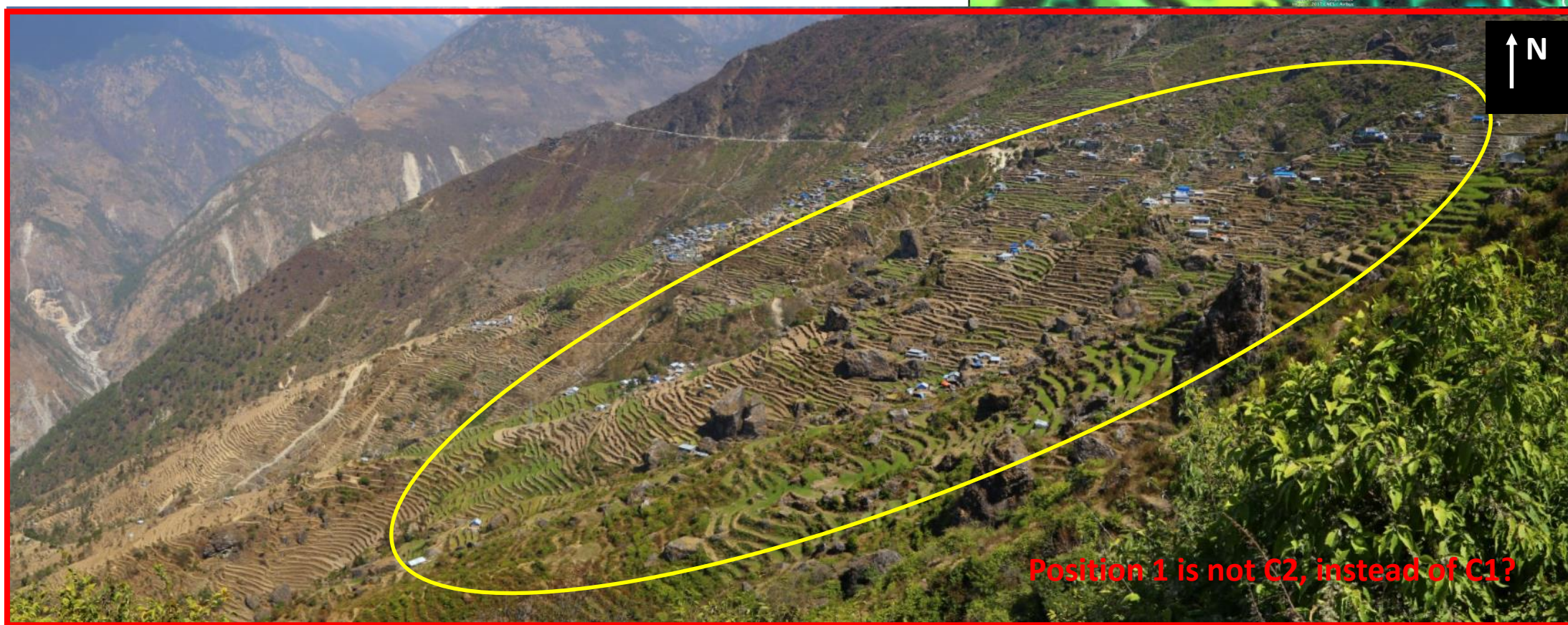
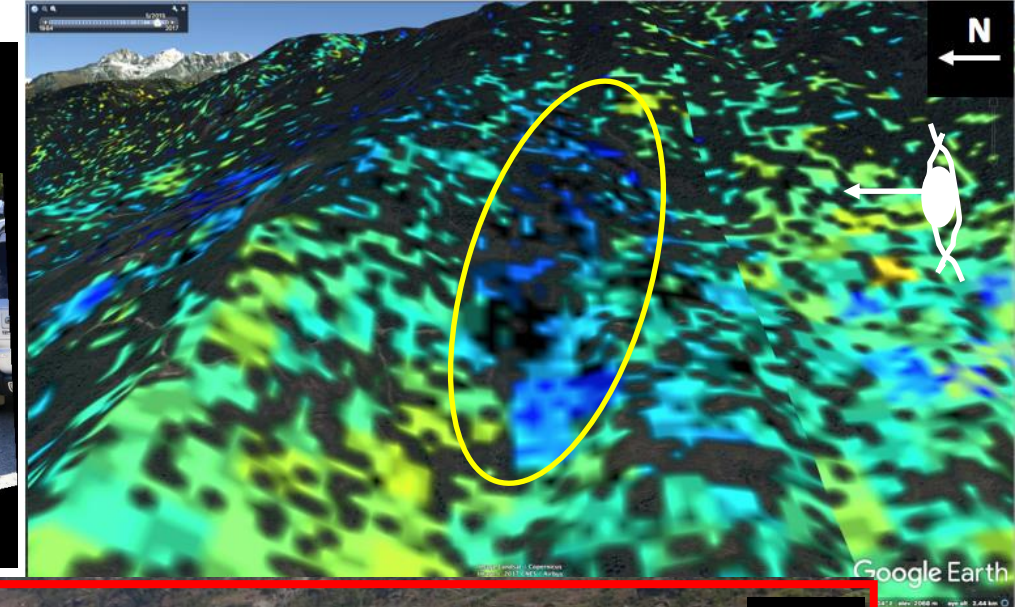












Position 1 is not C2, instead of C1?

The figure is a map of the Kilauea Iki Volcano area, showing the LOS rate (mm/yr) and the Landslide Database. The main map displays the LOS rate with a color scale from -50 (red) to 50 (blue) mm/yr. The Landslide Database is categorized into Definite (white), Probable (cross-hatched), and Questionable (dotted) landslides. The map also shows the locations of Historic (pink), Dormant Young (black), and Dormant Mature (blue) landslides. The map includes a scale bar (0 to 20 km) and a north arrow. The map is bounded by 35°0'N to 36°0'N latitude and 122°0'W to 121°0'W longitude. An inset map shows the location of the study area within the USA. Eight inset maps (A-H) provide detailed views of specific areas, each with a 1 km scale bar. A diagram in the bottom right corner illustrates the LOS (Line of Sight) and Vsat (Satellite) directions.

Summary

- SAR data can be used in a variety of ways to map landslides
- Detection success rate for SAR strongly related to:
 - Sensor resolution
 - Landslide orientation vs satellite acquisition geometry
 - Scattering changed from snow, precip, vegetation
- There is not a one-fit all SAR technique towards landslide mapping
 - Fast moving landslides
 - Slow moving landslides
 - Critical failure landslides
- Time-series InSAR capable of mapping slowly moving slides
 - Local detector successfully applied on regional processing to identify slowly moving landslide area's from superimposed noise sources

